

Using Trixi.jl for Adaptively Coupling Multiphysics Problems

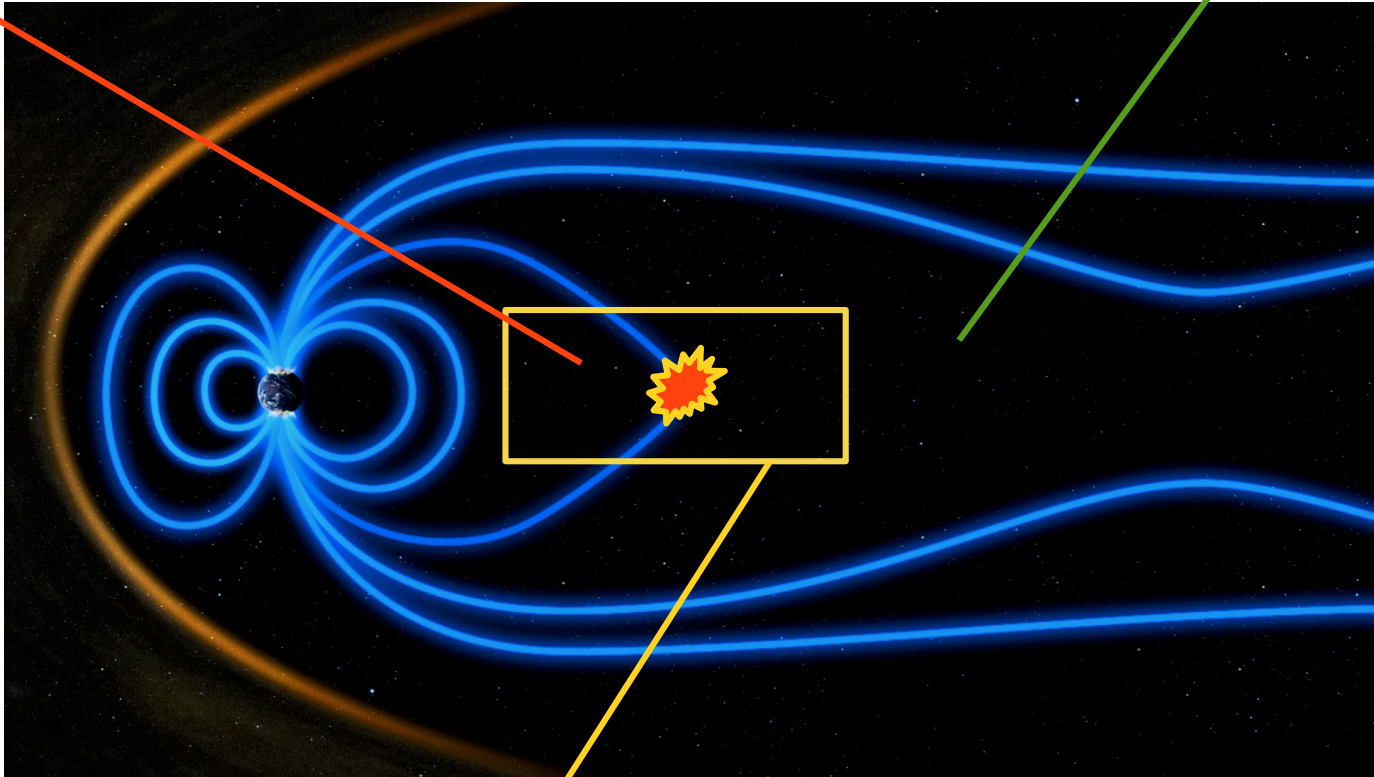
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Modeling

kinetic model
(expensive)

magnetohydrodynamics (MHD)
(cheap)



interface coupling

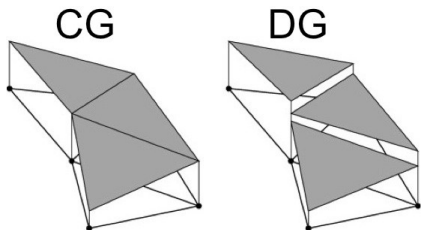
(ESA)



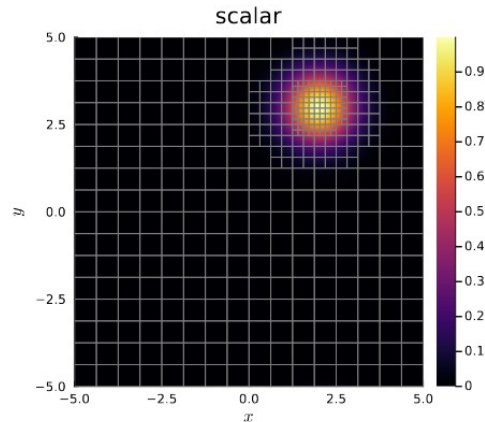
open source:
github.com/trixi-framework/Trixi.jl

Trixi.jl

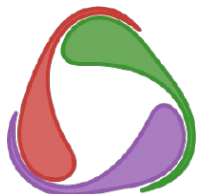
Discontinuous Galerkin



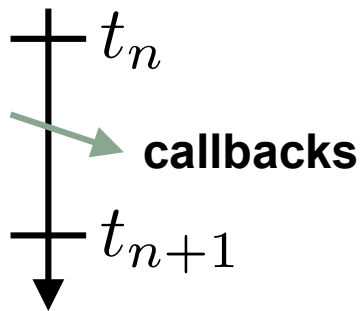
(Stack Overflow)



AMR



OrdinaryDiffEq (SciML)



using Trixi

```
equations = LinearScalarAdvectionEquation2D((0.5, -0.3))
solver = DGSEM(polydeg = 3)
cells_per_dimension = (16, 16)

mesh = StructuredMesh(cells_per_dimension, (-1, -1), (1, 1))

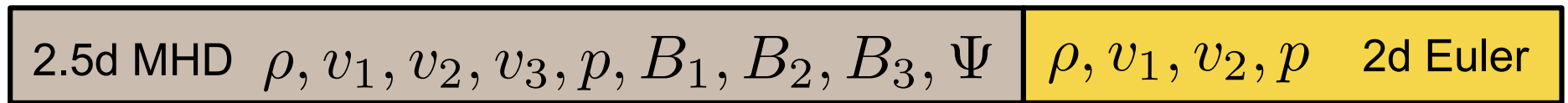
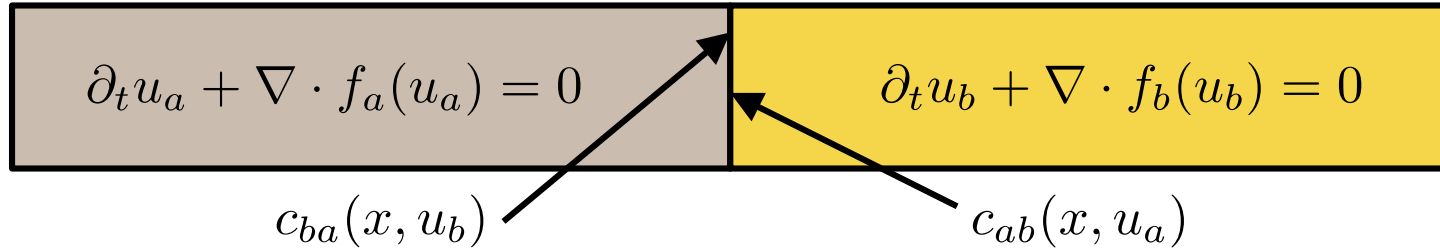
semi = SemidiscretizationHyperbolic(mesh, equations,
                                     initial_condition, solver)
ode = semidiscretize(semi, (0.0, 1.0));

stepsize_callback = StepsizeCallback(cfl = 1.6)
callbacks = CallbackSet(stepsize_callback)

sol = solve(ode, CarpenterKennedy2N54(),
            dt = 1.0, callback = callbacks);
```

Coupling via Converter Functions

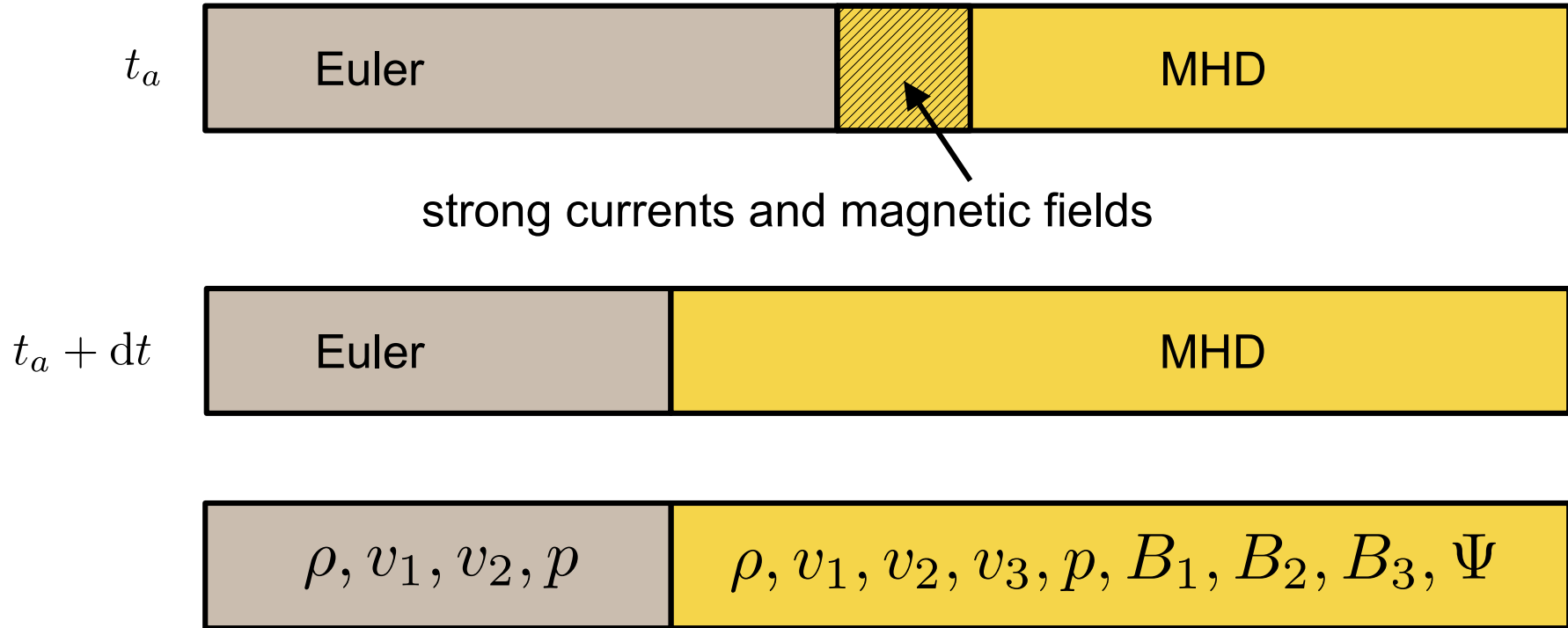
Two system with any number of shared variables, including 0:



```
coupling_function12 = (x, u, equations_other, equations_own)
                    -> SVector(u[1], u[2], u[3], 0.0, u[4], 0.0, 0.0, 0.0, 0.0)
coupling_function21 = (x, u, equations_other, equations_own) -> SVector(u[1], u[2], u[3], u[5])
```

- ➡ User can define converter functions.
- ➡ Any pair of systems can be coupled.

Adaptive Coupling



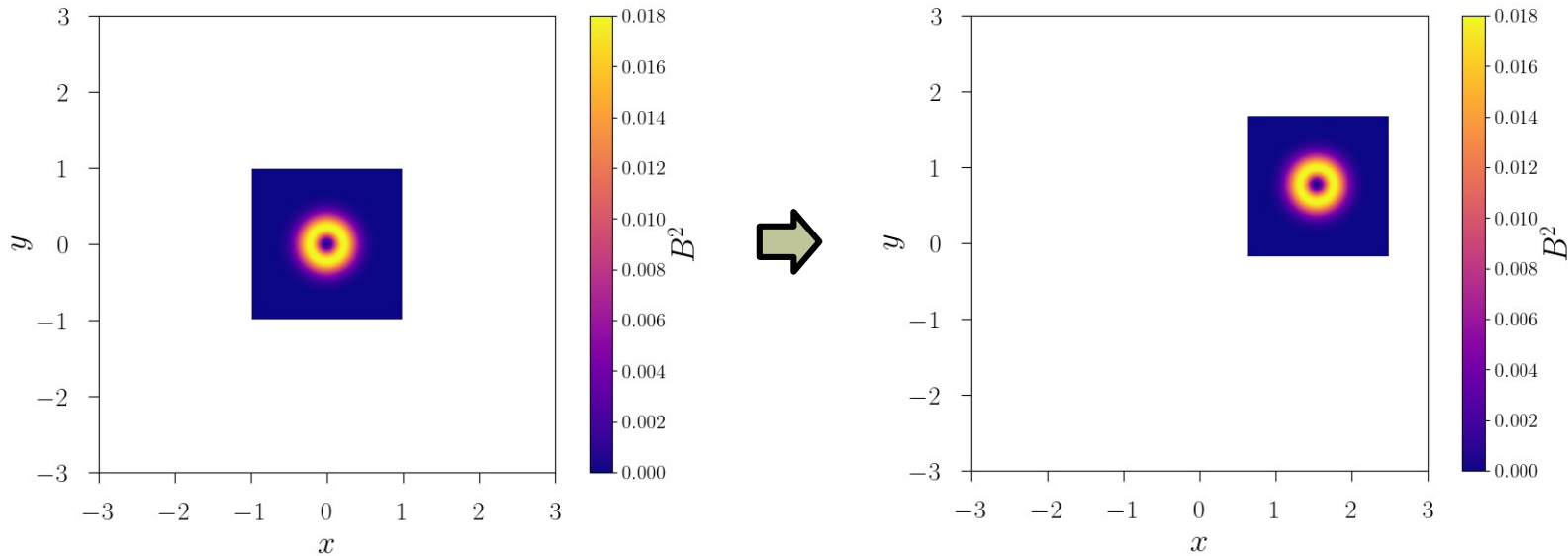
➡ Use callback functions to remesh.

➡ Use coupling functions to copy data.

Adaptive Model Selection

1. Generate the new grid (mesh views).
2. Write new u-solution vectors
3. Generate new ODE for OrdinaryDiffEq (integrator).
4. Reinitialize ODE integrator with new problem and new solution vector.

Euler and MHD



Time spent on coupled boundaries: 0.8%.

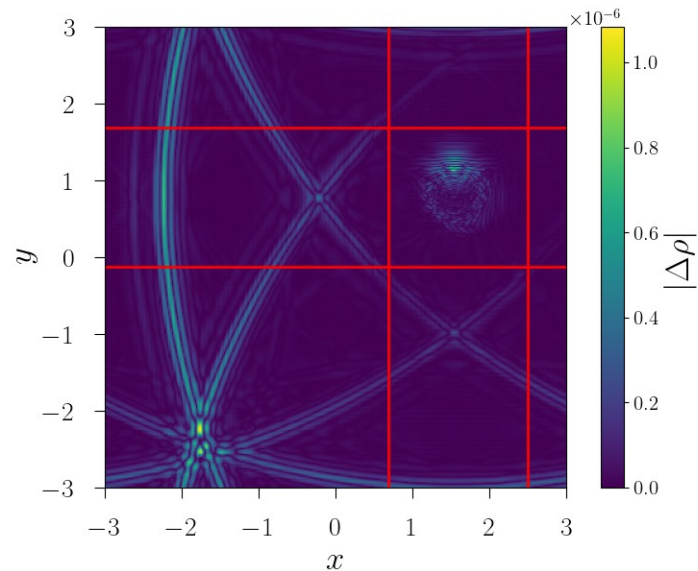
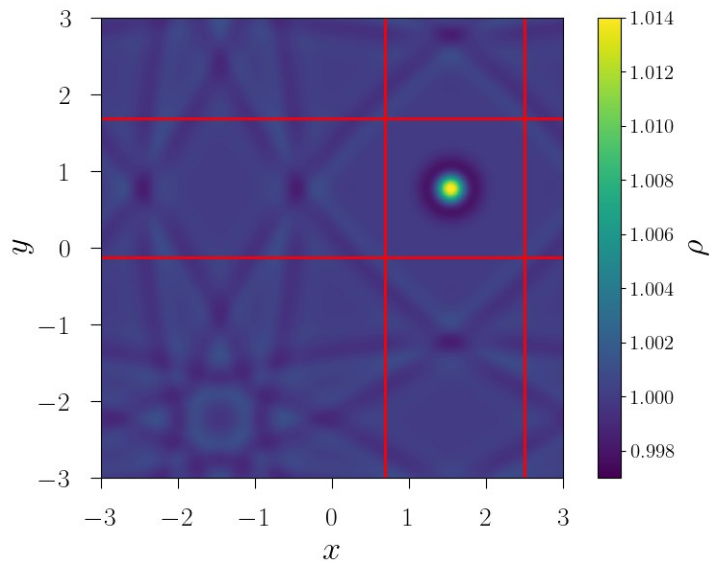
Time spent on model selection: 1.08s per model selection

Timings: coupled \rightarrow 765.6s

full MHD \rightarrow 1905.3s

Estimated maximum speed up: 3.31x; here: 2.49x

Density Evolution



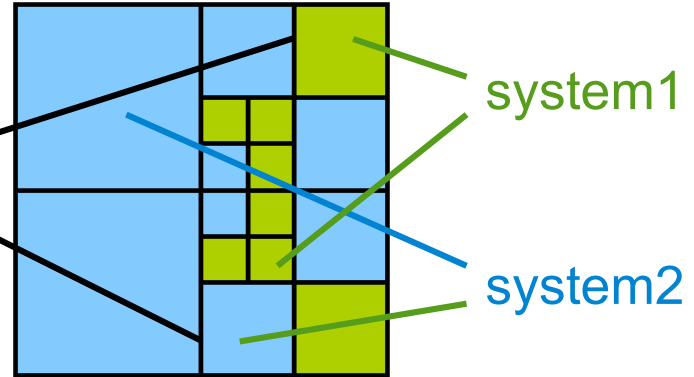
full MHD vs. coupled

➡ No artificial discontinuities.

➡ Small differences to full MHD simulation.

p4est Meshes

We can define the b.c. for each cell boundary.

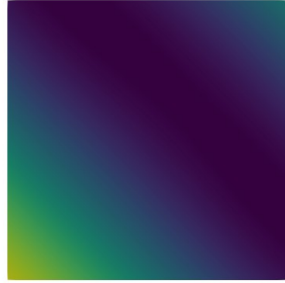
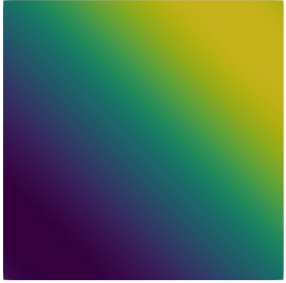


parent mesh

mesh views:



p4est Meshes



➡ p4est mesh views in Trixi.jl

➡ arbitrary topology

➡ views on smallest (cell) scale

➡ no coupling implemented yet



Conclusion

- ➔ Flexible coupling through converter functions.
- ➔ Free domain definitions.
- ➔ Adaptive coupling with arbitrary criteria.
- ➔ Coupled hierarchy of models.
- ➔ Non-simply connected mesh views in p4est