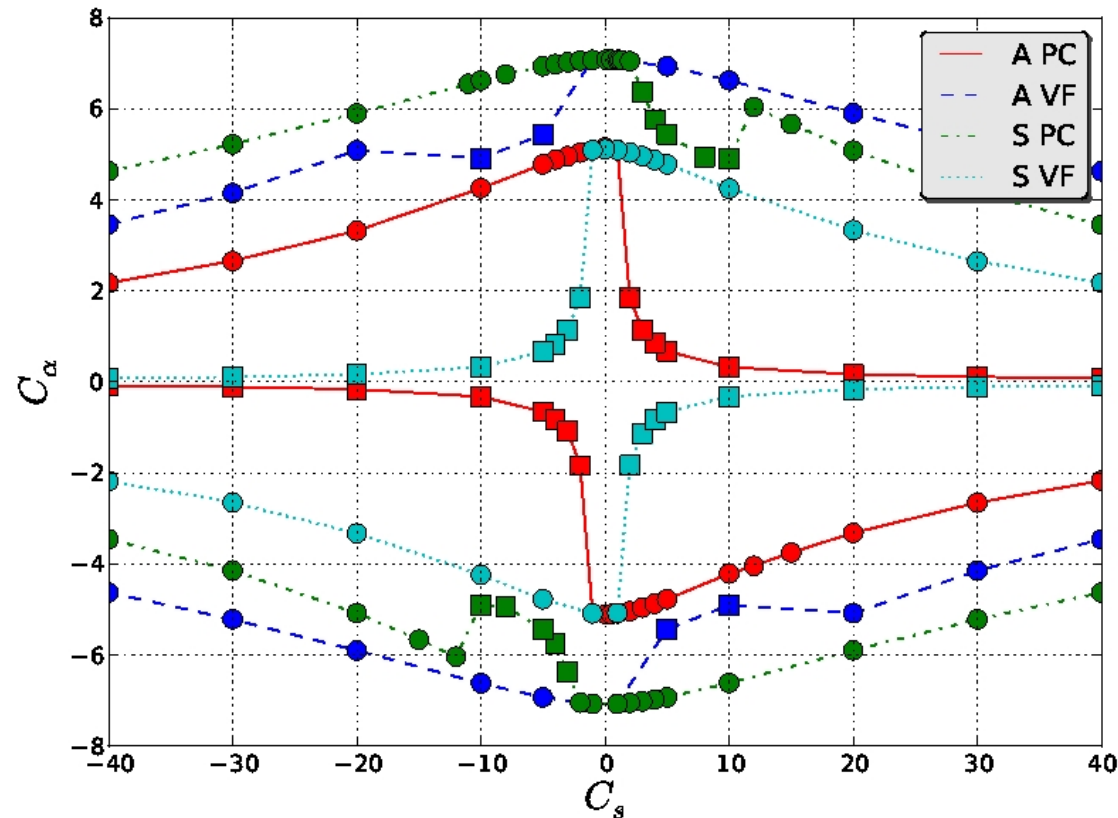


Magnetic helicity fluxes in dynamically quenched dynamamos

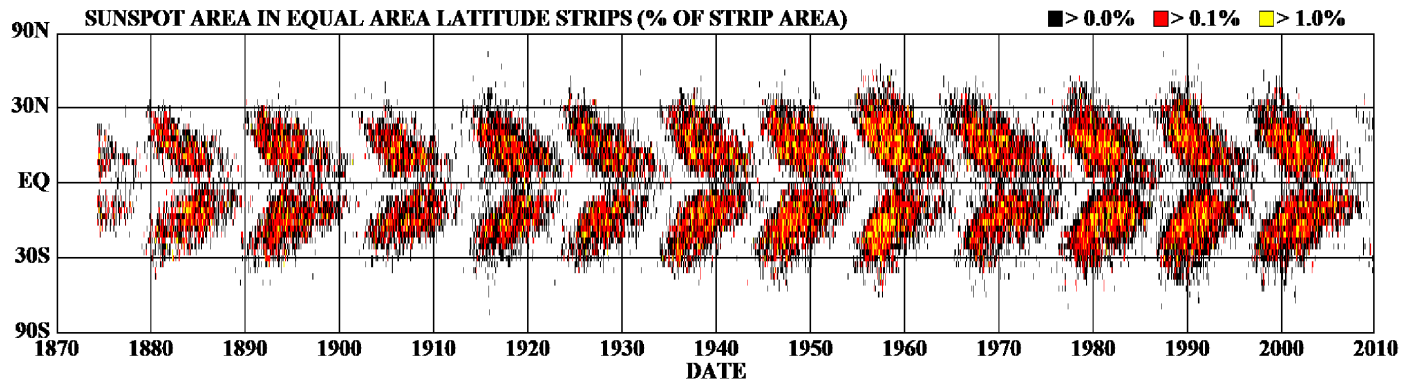
Simon Candelaresi



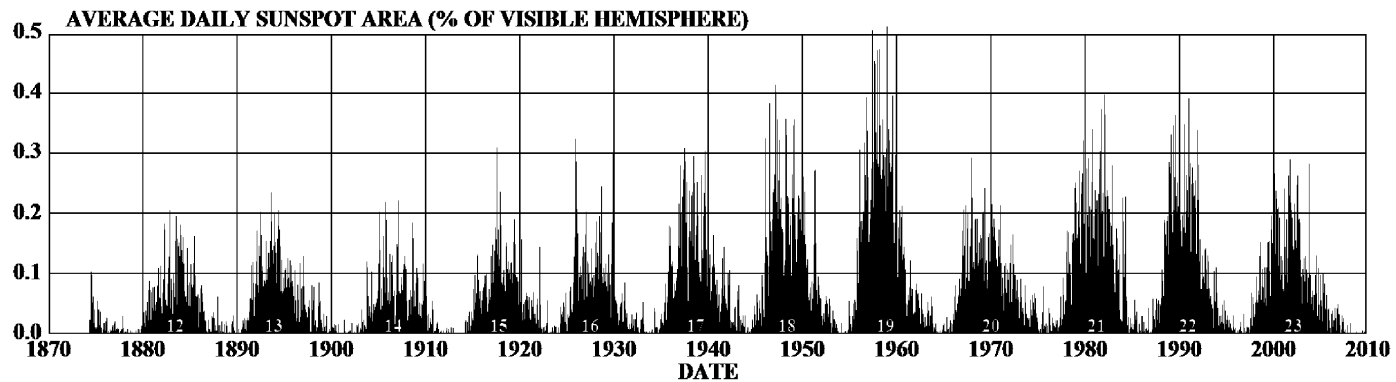
Solar Magnetic Field

11 year cycle

DAILY SUNSPOT AREA AVERAGED OVER INDIVIDUAL SOLAR ROTATIONS



蝶形图

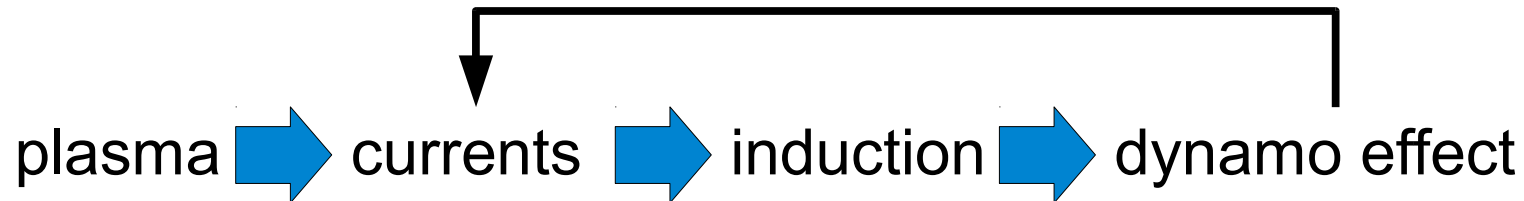


<http://solarscience.msfc.nasa.gov/>

HATHAWAY/NASA/MSFC 2009/11

 dynamo working

Dynamo Mechanism



Equations of **magnetohydrodynamics** (MHD):

Induction equation:
$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{U} \times \mathbf{B} - \eta \mathbf{J})$$

Momentum equation:
$$\frac{D\mathbf{U}}{Dt} = -c_S^2 \nabla \ln \rho + \mathbf{J} \times \mathbf{B} / \rho + \mathbf{F}_{\text{visc}}$$

Continuity equation:
$$\frac{D \ln \rho}{Dt} = -\nabla \cdot \mathbf{U}$$

Advective derivative:
$$D/Dt = \partial/\partial t + \mathbf{U} \cdot \nabla$$

Mean-Field Formalism

Mean-field decomposition: $B = \bar{B} + b$

Reynolds rules: $\overline{B_1 + B_2} = \bar{B}_1 + \bar{B}_2, \quad \overline{\bar{B}} = \bar{B}, \quad \bar{b} = 0$

$$\overline{\partial_\mu B} = \partial_\mu \bar{B}, \quad \mu = 0, 1, 2, 3$$

Mean-field induction equations:

$$\partial_t \bar{B} = \eta \nabla^2 \bar{B} + \nabla \times (\bar{U} \times \bar{B} + \bar{\mathcal{E}})$$

$$\partial_t b = \nabla \times (\bar{U} \times b + G) + \nabla \times (u \times \bar{B}) + \eta \nabla^2 b$$

Electromotive force (emf): $\bar{\mathcal{E}} = \overline{u \times b}$

$$G = u \times b - \overline{u \times b}$$

Electromotive Force

The EMF is assumed to be linear and homogeneous in \overline{B} .

$$\begin{aligned} \Rightarrow \mathcal{E}_i(x, t) &= \mathcal{E}_i^{(0)}(x, t) \\ &+ \int \int_{\alpha} K_{ij}(x, x', t, t') \overline{B}_j(x - x', t - t') d^3x' dt' \end{aligned}$$

Taylor expansion:

$$\overline{B}_j(x', t) = \overline{B}_j(x, t) + (x'_k - x_k) \frac{\partial \overline{B}_j(x, t)}{\partial x_k} + \dots$$

Assume local and instantaneous dependence of $\overline{\mathcal{E}}$ on \overline{B} .

$$\Rightarrow \overline{\mathcal{E}}_i = \alpha_{ij} \overline{B}_j + b_{ijk} \frac{\partial \overline{B}_j}{\partial x_k} + \dots$$

For a turbulent system without preferred direction, i.e. $U = 0$:

$$\overline{\mathcal{E}} = \alpha \overline{B} - \eta_t \nabla \times \overline{B}$$

$$\partial_t \overline{B} = \alpha \nabla \times \overline{B} + \eta_T \nabla^2 \overline{B}$$

Alpha-Effect

α effect: $\alpha = \alpha_K + \alpha_M$

$$\alpha_K = -\tau \overline{\boldsymbol{\omega} \cdot \mathbf{u}} / 3$$

$$\alpha_M = \tau \overline{\mathbf{j} \cdot \mathbf{b}} / (3\bar{\rho}) = \tau k^2 \overline{\mathbf{a} \cdot \mathbf{b}} / (3\bar{\rho}) = \bar{h}_m$$

helically driven dynamo $\bar{h}_{K,f} = \overline{\boldsymbol{\omega} \cdot \mathbf{u}}$

➔ production of magnetic helicity $\bar{h}_{M,f} = \overline{\mathbf{a} \cdot \mathbf{b}}$

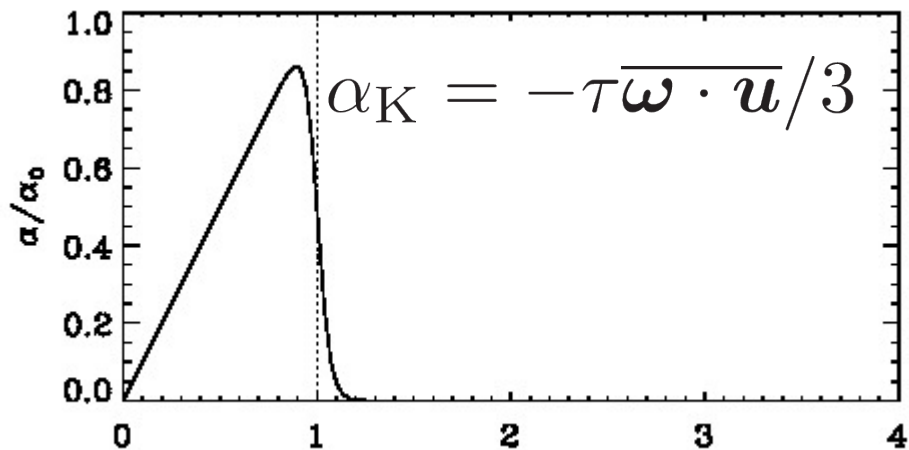
➔ total magnetic helicity conservation $\bar{h}_{M,m} = \overline{\mathbf{A} \cdot \mathbf{B}}$

$\overline{\mathbf{a} \cdot \mathbf{b}}$ works against dynamo: $E_M \propto 1/\text{Re}_M$ $\text{Re}_M = \frac{UL}{\eta}$

Sun: $\text{Re}_M = 10^9$ galaxies: $\text{Re}_M = 10^{18}$

Magnetic Helicity Fluxes

$$\frac{\partial \alpha_M}{\partial t} = -2\eta_t k_f^2 \left(\frac{\overline{\boldsymbol{\varepsilon}} \cdot \overline{\mathbf{B}}}{B_{\text{eq}}^2} + \frac{\alpha_M}{R_m} \right) - \frac{\partial}{\partial z} \overline{\mathcal{F}}_\alpha$$

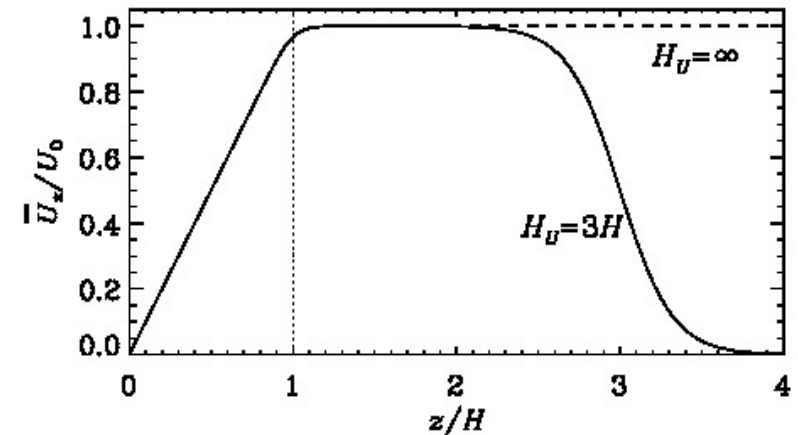


advective:
 $\alpha_M \overline{U}$

α diffusion
 $k_\alpha \frac{\partial \alpha_M}{\partial z}$

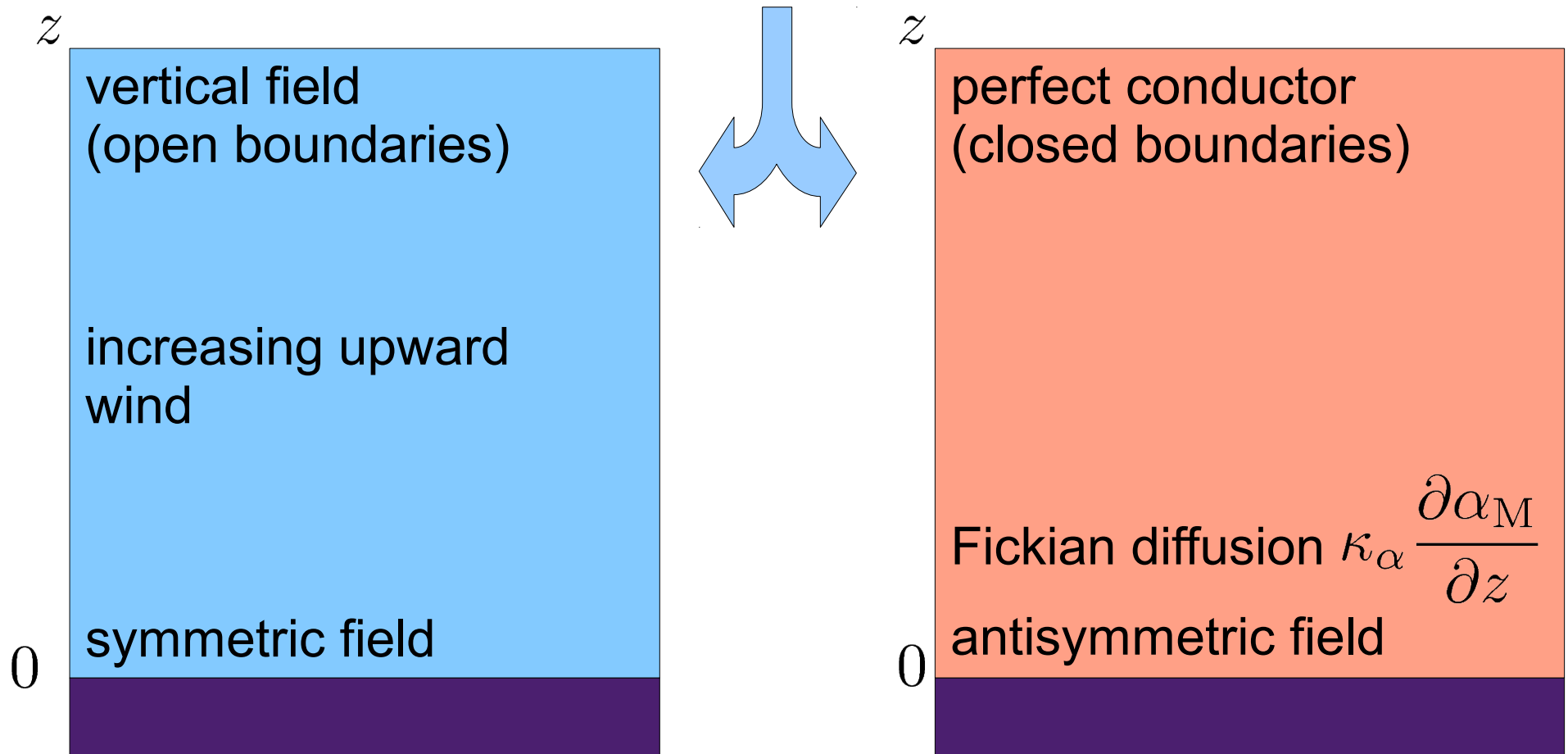
$$\frac{\partial \overline{h}_m}{\partial t} = 2\overline{\boldsymbol{\varepsilon}} \cdot \overline{\mathbf{B}} - 2\eta\mu_0 \overline{\mathbf{J}} \cdot \overline{\mathbf{B}} - \nabla \cdot \overline{\mathbf{F}}_m$$

$$\frac{\partial \overline{h}_f}{\partial t} = -2\overline{\boldsymbol{\varepsilon}} \cdot \overline{\mathbf{B}} - 2\eta\mu_0 \overline{\mathbf{j}} \cdot \overline{\mathbf{b}} - \nabla \cdot \overline{\mathbf{F}}_f$$



Magnetic helicity fluxes

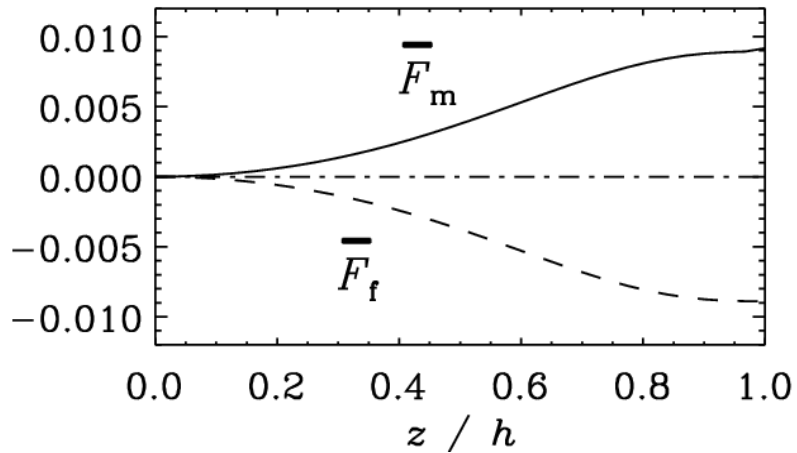
Solve equations for one hemisphere.
Impose (anti)symmetric field at the equator.



$$\text{Re}_M = \frac{U_{\text{rms}} L}{\eta}$$

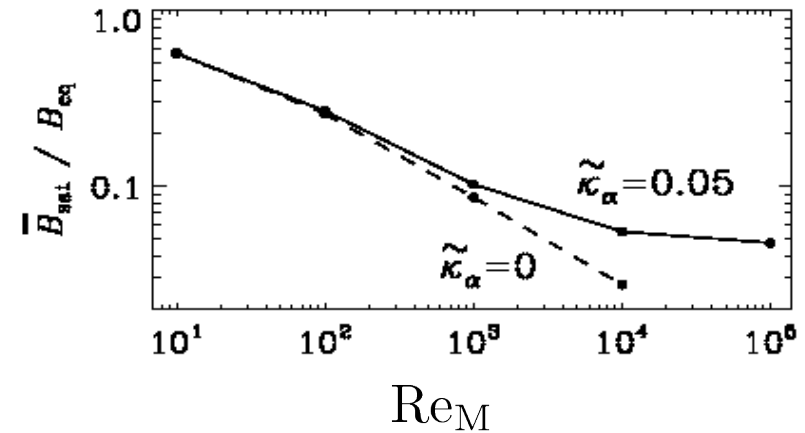
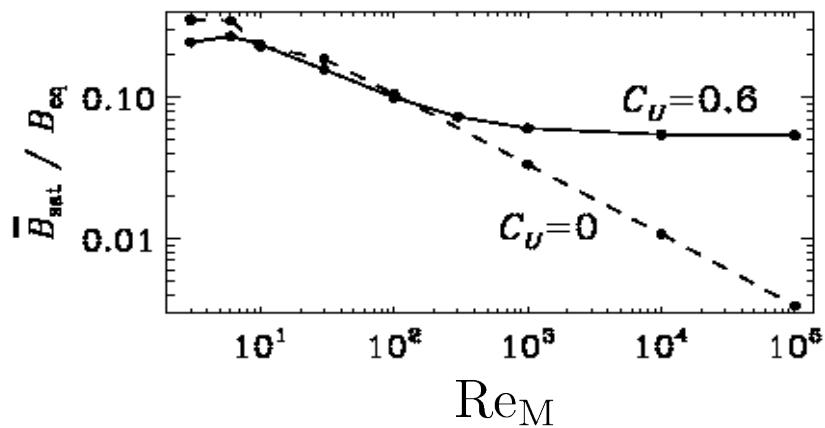
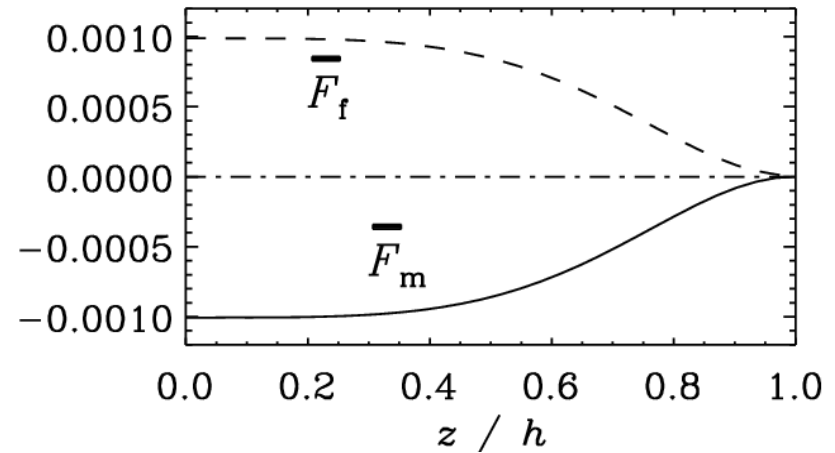
Magnetic helicity fluxes

open boundary
symmetric
wind



vs.

closed boundary
antisymmetric
 κ_α

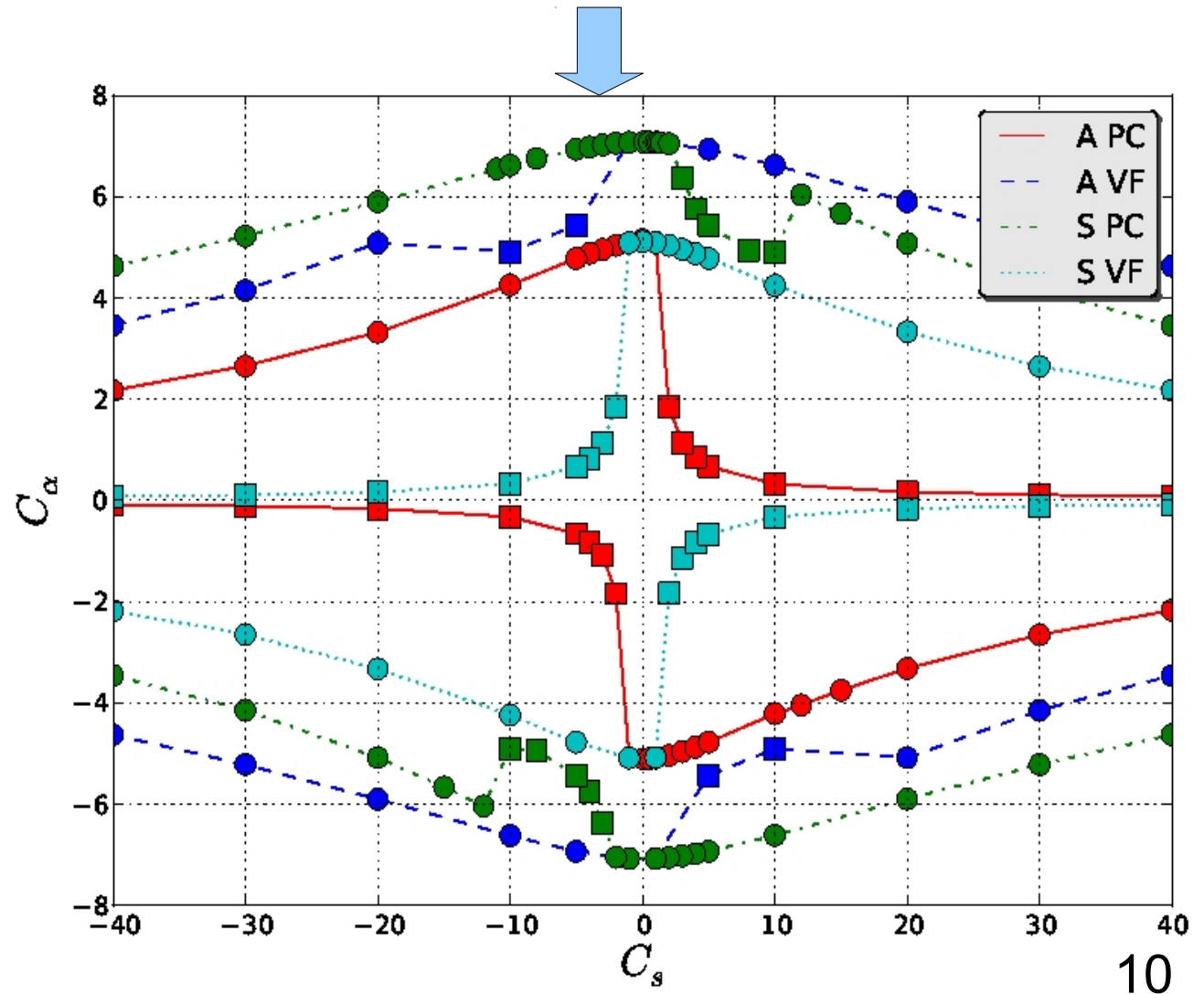


Adding shear

Critical values for the forcing and the shearing amplitude

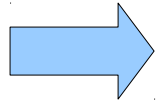
Shearing velocity field:

$$\bar{\mathbf{U}} = \begin{pmatrix} 0 \\ Sz \\ 0 \end{pmatrix}$$

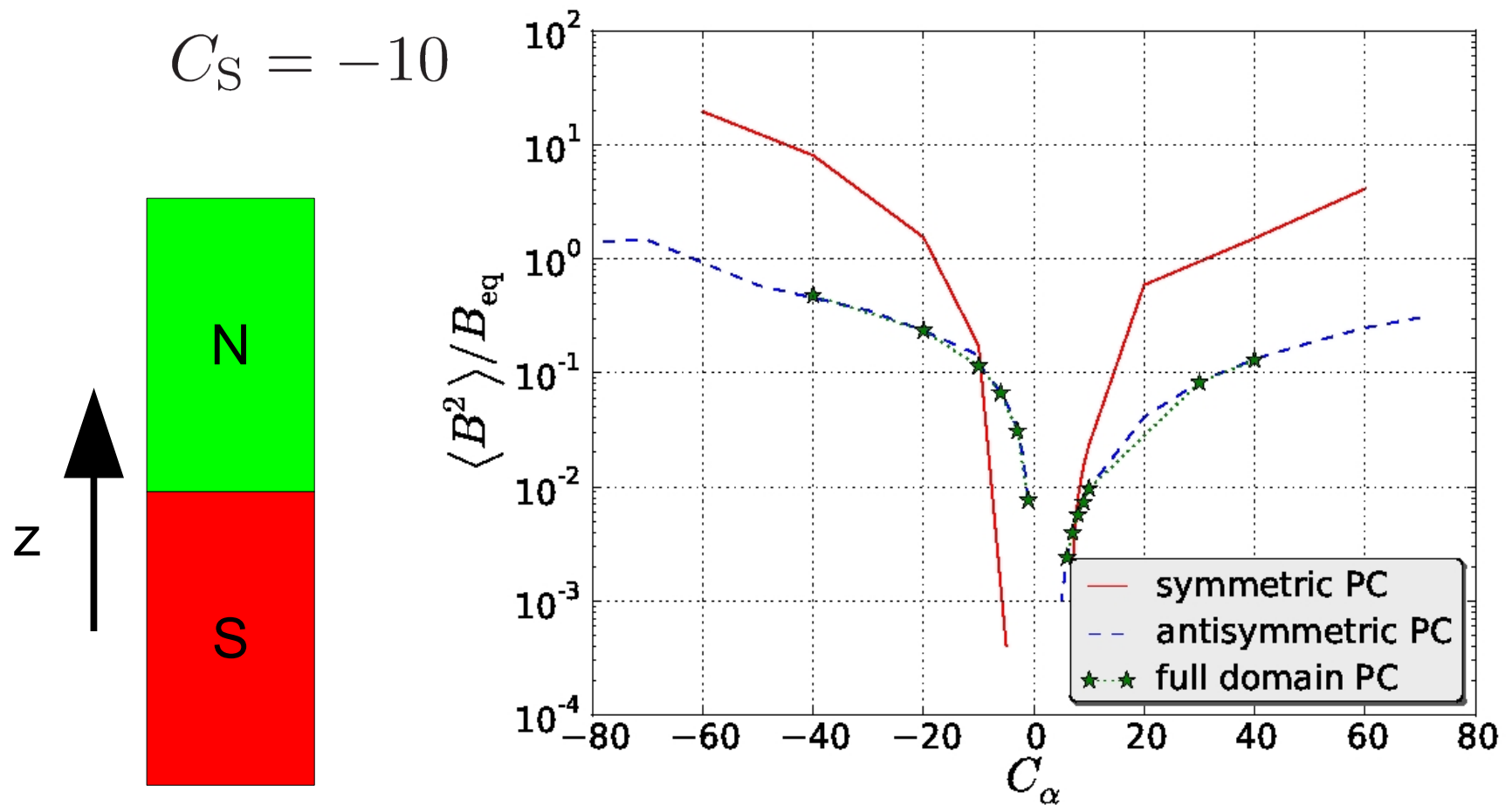


Full domain

Imposed parity in the hemispheric model is artificial.



Include both hemispheres.

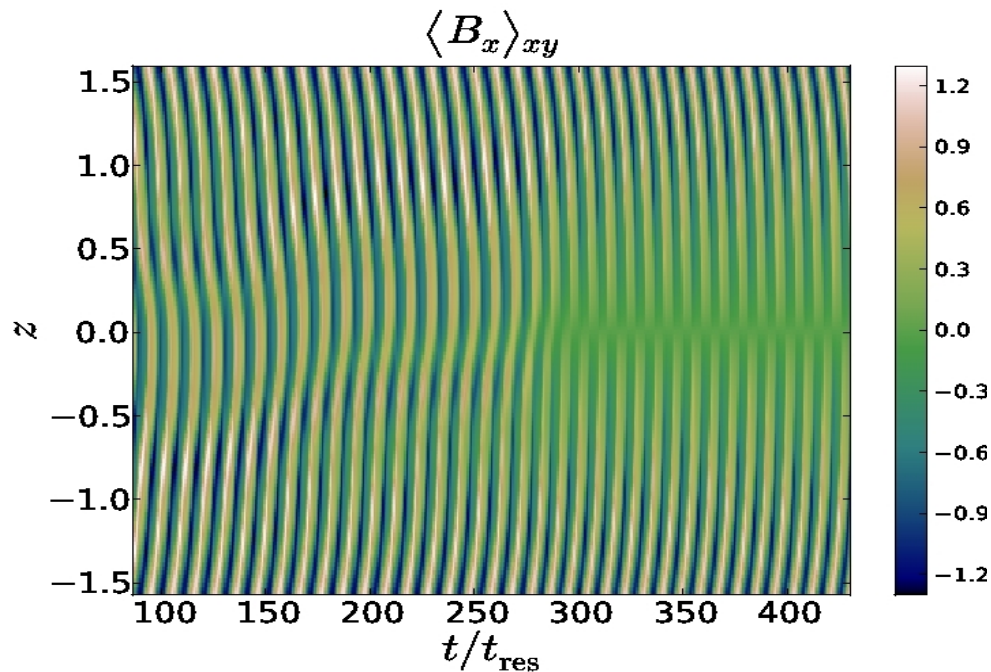


Preferred antisymmetric mode? 11

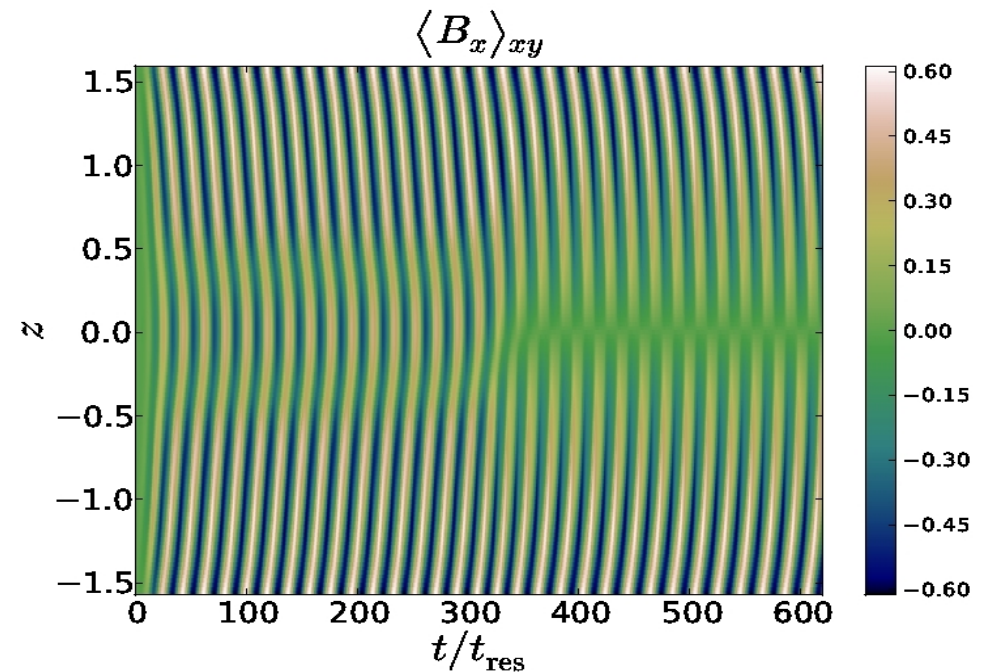
Parity change

Look at the parity of the magnetic field \overline{B}_y

Random initial field



Symmetric initial field



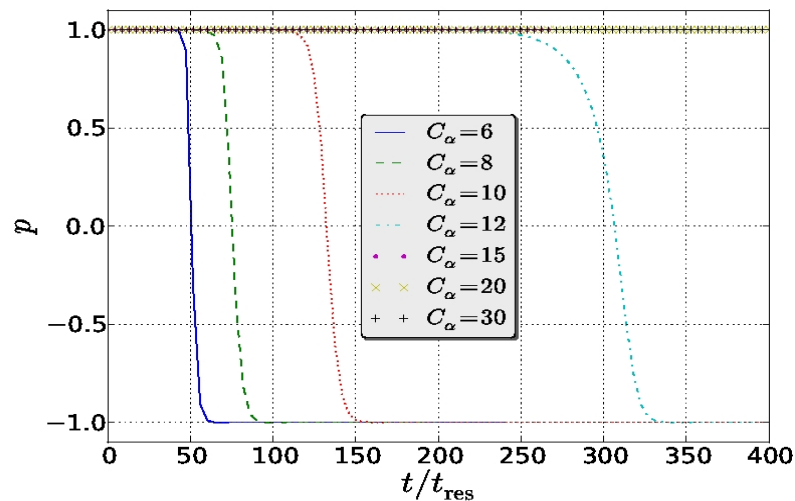
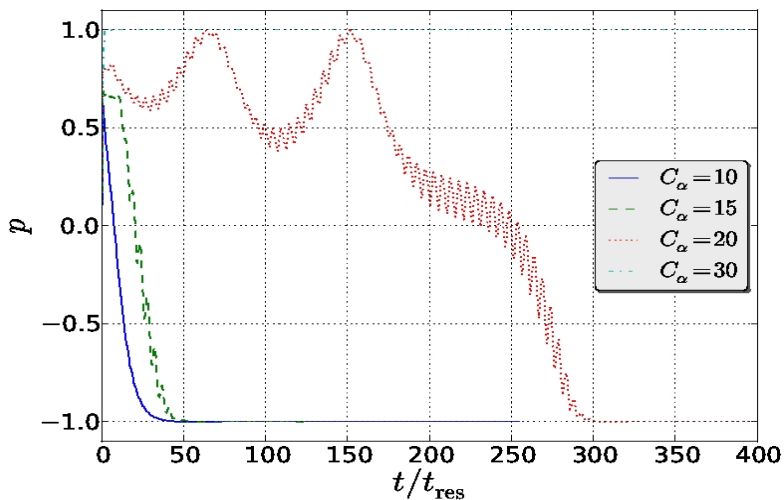
The antisymmetric solution seems to be the preferred one.

Parity change

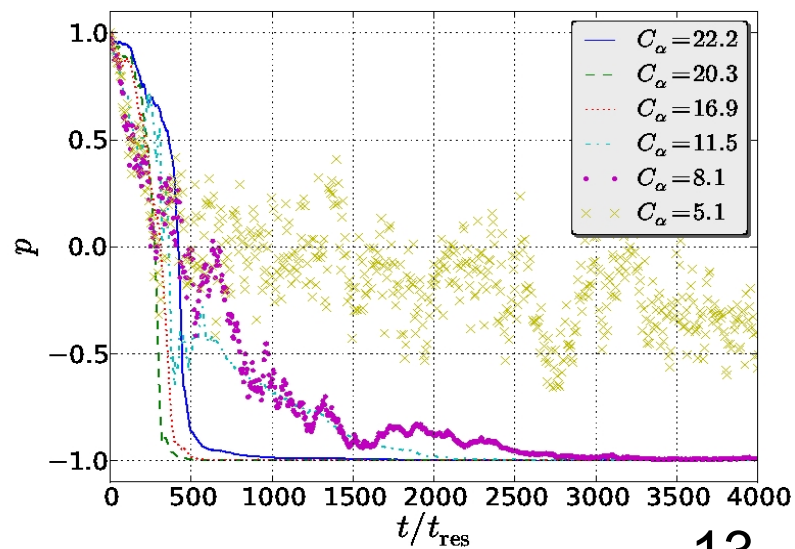
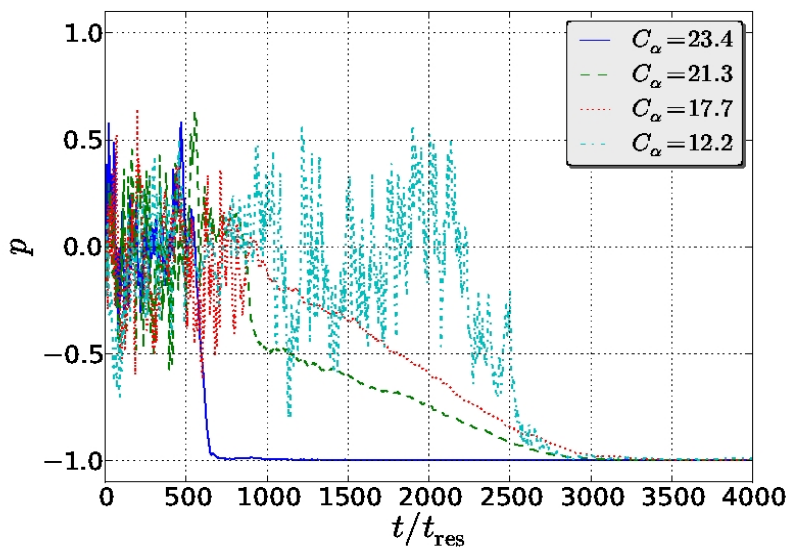
Random initial field

Symmetric initial field

MF



DNS



Conclusions

- Advective magnetic helicity fluxes can alleviate catastrophic quenching.
- Diffusive magnetic helicity fluxes can alleviate catastrophic quenching.

- Symmetric mode is unstable.
- The antisymmetric mode seems to be the preferred one.
- Check the growth rate of the modes.

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Axel Brandenburg, Simon Candelaresi and Piyali Chatterjee.

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Bifurcation behavior of dynamically quenched dynamos.

Appendix

Viscous force: $\mathbf{F}_{\text{visc}} = \rho^{-1} \nabla \cdot 2\nu\rho\mathbf{S}$

Strain tensor: $S_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) - \frac{1}{3}\delta_{ij} \nabla \cdot \mathbf{U}$

Sound speed: $c_S = \sqrt{\gamma \frac{p}{\rho}}$